

V Vektoranalysis

V.1 Vektor-Identitäten

$$(\mathbf{a} \wedge \mathbf{b}) \wedge \mathbf{c} = (\mathbf{a} \cdot \mathbf{c})\mathbf{b} - (\mathbf{b} \cdot \mathbf{c})\mathbf{a} \quad (\text{V.1})$$

$$\nabla \wedge \nabla \Phi = 0 \quad (\text{V.2})$$

$$\nabla \cdot (\nabla \wedge \mathbf{f}) = 0 \quad (\text{V.3})$$

$$\nabla \cdot (\Phi \mathbf{f}) = \Phi \nabla \cdot \mathbf{f} + \mathbf{f} \cdot \nabla \Phi \quad (\text{V.4})$$

$$\nabla \wedge (\Phi \mathbf{f}) = \Phi \nabla \wedge \mathbf{f} + (\nabla \Phi) \wedge \mathbf{f} \quad (\text{V.5})$$

$$\nabla \wedge (\mathbf{f} \wedge \mathbf{g}) = (\mathbf{g} \cdot \nabla) \mathbf{f} - (\mathbf{f} \cdot \nabla) \mathbf{g} + \mathbf{f} (\nabla \cdot \mathbf{g}) - \mathbf{g} (\nabla \cdot \mathbf{f}) \quad (\text{V.6})$$

$$\nabla \cdot (\mathbf{f} \wedge \mathbf{g}) = \mathbf{g} \cdot (\nabla \wedge \mathbf{f}) - \mathbf{f} \cdot (\nabla \wedge \mathbf{g}) \quad (\text{V.7})$$

$$\nabla (\mathbf{f} \cdot \mathbf{g}) = \mathbf{f} \wedge (\nabla \wedge \mathbf{g}) + \mathbf{g} \wedge (\nabla \wedge \mathbf{f}) + (\mathbf{f} \cdot \nabla) \mathbf{g} + (\mathbf{g} \cdot \nabla) \mathbf{f} \quad (\text{V.8})$$

$$(\mathbf{f} \cdot \nabla) \mathbf{f} = (\nabla \wedge \mathbf{f}) \wedge \mathbf{f} + \nabla \left(\frac{1}{2} \mathbf{f}^2 \right) \quad (\text{V.9})$$

$$\Delta \mathbf{f} = \nabla (\nabla \cdot \mathbf{f}) - \nabla \wedge (\nabla \wedge \mathbf{f}) \quad (\text{V.10})$$

V.2 Satz von Gauß

Satz von Gauß

$$\int_A \mathbf{f} \cdot \mathbf{n} \, dA = \int_V \nabla \cdot \mathbf{f} \, dV \quad \text{bzw.} \quad \int_A f_j n_j \, dA = \int_V f_{j,j} \, dV \quad (\text{V.11})$$

Konsequenz 1

$$\int_A \Phi \mathbf{n} \, dA = \int_V \nabla \Phi \, dV \quad \text{bzw.} \quad \int_A \Phi n_j \, dA = \int_V \frac{\partial \Phi}{\partial x_j} \, dV \quad (\text{V.12})$$

Konsequenz 2

$$\int_A \sigma_{ij} n_j \, dA = \int_V \sigma_{ij,j} \, dV \quad (\text{V.13})$$

Konsequenz 3

$$\int_A \mathbf{f} \wedge \mathbf{n} \, dA = - \int_V \nabla \wedge \mathbf{f} \, dV \quad (\text{V.14})$$

Konsequenz 4

$$\int_A (\nabla\Phi) \cdot \mathbf{n} \, dA = \int_V \Delta\Phi \, dV \quad (\text{V.15})$$

Konsequenz 5 (1. Greenscher Satz)

$$\int_A \Phi \frac{\partial\Psi}{\partial n} \, dA = \int_V (\Phi\Delta\Psi + \nabla\Phi \cdot \nabla\Psi) \, dV \quad (\text{V.16})$$

Konsequenz 6 (2. Greenscher Satz)

$$\int_A \left(\Phi \frac{\partial\Psi}{\partial n} - \Psi \frac{\partial\Phi}{\partial n} \right) \, dA = \int_V (\Phi\Delta\Psi - \Psi\Delta\Phi) \, dV \quad (\text{V.17})$$

V.3 Satz von Stokes**Satz von Stokes**

$$\int_C \mathbf{f} \cdot d\mathbf{x} = \int_A (\nabla \wedge \mathbf{f}) \cdot \mathbf{n} \, dA \quad (\text{V.18})$$

Konsequenz 1

$$\int_C u \, dx + v \, dy = \int_A \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right) \, dx \, dy \quad (\text{V.19})$$

Konsequenz 2

$$\int_C \Phi \, dx = - \int_A (\nabla\Phi) \wedge \mathbf{n} \, dA \quad (\text{V.20})$$

V.4 Zylinderkoordinaten**Umrechnung**

$$x = r \cos \varphi, \quad y = r \sin \varphi, \quad z = z \quad (\text{V.21})$$

$$r = \sqrt{x^2 + y^2}, \quad \tan \varphi = \frac{y}{x}, \quad z = z \quad (\text{V.22})$$

$$\mathbf{e}_r = \cos \varphi \, \mathbf{e}_x + \sin \varphi \, \mathbf{e}_y, \quad \mathbf{e}_\varphi = -\sin \varphi \, \mathbf{e}_x + \cos \varphi \, \mathbf{e}_y, \quad \mathbf{e}_z = \mathbf{e}_z \quad (\text{V.23})$$

$$\mathbf{e}_x = \cos \varphi \, \mathbf{e}_r - \sin \varphi \, \mathbf{e}_\varphi, \quad \mathbf{e}_y = \sin \varphi \, \mathbf{e}_r + \cos \varphi \, \mathbf{e}_\varphi, \quad \mathbf{e}_z = \mathbf{e}_z \quad (\text{V.24})$$

Ableitung der Einheitsvektoren Die ersten Ableitungen der Einheitsvektoren nach r , φ und z sind null bis auf

$$\frac{\partial \mathbf{e}_r}{\partial \varphi} = \mathbf{e}_\varphi, \quad \frac{\partial \mathbf{e}_\varphi}{\partial \varphi} = -\mathbf{e}_r \quad (\text{V.25})$$

Gradient

$$\nabla \Phi = \frac{\partial \Phi}{\partial r} \mathbf{e}_r + \frac{1}{r} \frac{\partial \Phi}{\partial \varphi} \mathbf{e}_\varphi + \frac{\partial \Phi}{\partial z} \mathbf{e}_z \quad (\text{V.26})$$

Divergenz

$$\nabla \cdot \mathbf{f} = \frac{1}{r} \frac{\partial}{\partial r} (r f_r) + \frac{1}{r} \frac{\partial f_\varphi}{\partial \varphi} + \frac{\partial f_z}{\partial z} \quad (\text{V.27})$$

Rotation

$$\nabla \wedge \mathbf{f} = \frac{1}{r} \begin{vmatrix} \mathbf{e}_r & r\mathbf{e}_\varphi & \mathbf{e}_z \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \varphi} & \frac{\partial}{\partial z} \\ f_r & r f_\varphi & f_z \end{vmatrix} \quad (\text{V.28})$$

$$= \left(\frac{1}{r} \frac{\partial f_z}{\partial \varphi} - \frac{\partial f_\varphi}{\partial z} \right) \mathbf{e}_r + \left(\frac{\partial f_r}{\partial z} - \frac{\partial f_z}{\partial r} \right) \mathbf{e}_\varphi + \frac{1}{r} \left(\frac{\partial (f_\varphi r)}{\partial r} - \frac{\partial f_r}{\partial \varphi} \right) \mathbf{e}_z \quad (\text{V.29})$$

Laplace-Operator (skalar)

$$\Delta \Phi = \frac{\partial^2 \Phi}{\partial r^2} + \frac{1}{r} \frac{\partial \Phi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \Phi}{\partial \varphi^2} + \frac{\partial^2 \Phi}{\partial z^2} \quad (\text{V.30})$$

Laplace-Operator (vektoriell)

$$\Delta \mathbf{f} = \left(\Delta f_r - \frac{1}{r^2} \left[f_r + 2 \frac{\partial f_\varphi}{\partial \varphi} \right] \right) \mathbf{e}_r + \left(\Delta f_\varphi - \frac{1}{r^2} \left[f_\varphi - 2 \frac{\partial f_r}{\partial \varphi} \right] \right) \mathbf{e}_\varphi + (\Delta f_z) \mathbf{e}_z \quad (\text{V.31})$$

$\mathbf{u} \cdot \nabla$

$$\mathbf{u} \cdot \nabla = u_r \frac{\partial}{\partial r} + \frac{u_\varphi}{r} \frac{\partial}{\partial \varphi} + u_z \frac{\partial}{\partial z} \quad (\text{V.32})$$

Divergenz eines Tensors

$$\nabla \cdot \boldsymbol{\sigma} = \left(\frac{1}{r} \frac{\partial (\sigma_{rr} r)}{\partial r} + \frac{1}{r} \frac{\partial \sigma_{\varphi r}}{\partial \varphi} + \frac{\partial \sigma_{zr}}{\partial z} - \frac{\sigma_{\varphi\varphi}}{r} \right) \mathbf{e}_r$$

$$\begin{aligned}
& + \left(\frac{1}{r} \frac{\partial(\sigma_{r\varphi} r)}{\partial r} + \frac{1}{r} \frac{\partial\sigma_{\varphi\varphi}}{\partial\varphi} + \frac{\partial\sigma_{z\varphi}}{\partial z} + \frac{\sigma_{r\varphi}}{r} \right) \mathbf{e}_\varphi \\
& + \left(\frac{1}{r} \frac{\partial(\sigma_{rz} r)}{\partial r} + \frac{1}{r} \frac{\partial\sigma_{\varphi z}}{\partial\varphi} + \frac{\partial\sigma_{zz}}{\partial z} \right) \mathbf{e}_z
\end{aligned} \tag{V.33}$$

V.4.1 Wärmeleitungsgleichung

Wärmefluss

$$\mathbf{q} = -k\nabla T = -k \left(\frac{\partial T}{\partial r} \mathbf{e}_r + \frac{1}{r} \frac{\partial T}{\partial\varphi} \mathbf{e}_\varphi + \frac{\partial T}{\partial z} \mathbf{e}_z \right) \tag{V.34}$$

Wärmeleitungsgleichung ($k = \text{const}$)

$$\rho C \frac{\partial T}{\partial t} - k \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial T}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 T}{\partial\varphi^2} + \frac{\partial^2 T}{\partial z^2} \right] = Q \tag{V.35}$$

V.4.2 Navier–Stokes–Gleichung

Dehnraten–Tensor

$$e_{rr} = \frac{\partial u_r}{\partial r}, \quad e_{\varphi\varphi} = \frac{1}{r} \frac{\partial u_\varphi}{\partial\varphi} + \frac{1}{r} u_r, \quad e_{zz} = \frac{\partial u_z}{\partial z} \tag{V.36}$$

$$2e_{r\varphi} = 2e_{\varphi r} = r \frac{\partial(r^{-1}u_\varphi)}{\partial r} + \frac{1}{r} \frac{\partial u_r}{\partial\varphi} \tag{V.37}$$

$$2e_{rz} = 2e_{zr} = \frac{\partial u_r}{\partial z} + \frac{\partial u_z}{\partial r} \tag{V.38}$$

$$2e_{\varphi z} = 2e_{z\varphi} = \frac{1}{r} \frac{\partial u_z}{\partial\varphi} + \frac{\partial u_\varphi}{\partial z} \tag{V.39}$$

Kontinuitätsgleichung ($\rho \neq \text{const}$)

$$\frac{\partial\rho}{\partial t} + \frac{1}{r} \frac{\partial}{\partial r}(\rho u_r r) + \frac{1}{r} \frac{\partial}{\partial\varphi}(\rho u_\varphi) + \frac{\partial}{\partial z}(\rho u_z) = 0 \tag{V.40}$$

Kontinuitätsgleichung ($\rho = \text{const}$)

$$\frac{1}{r} \frac{\partial(u_r r)}{\partial r} + \frac{1}{r} \frac{\partial u_\varphi}{\partial\varphi} + \frac{\partial u_z}{\partial z} = 0 \tag{V.41}$$

Navier–Stokes–Gleichung ($\rho, \eta = \text{const}$)

$$\begin{aligned} & \rho \left(\frac{\partial u_r}{\partial t} + u_r \frac{\partial u_r}{\partial r} + u_z \frac{\partial u_r}{\partial z} + \frac{1}{r} \left[u_\varphi \frac{\partial u_r}{\partial \varphi} - u_\varphi^2 \right] \right) \\ & = -\frac{\partial p}{\partial r} + \eta \left(\Delta u_r - \frac{1}{r^2} \left[u_r + 2 \frac{\partial u_\varphi}{\partial \varphi} \right] \right) \end{aligned} \quad (\text{V.42})$$

$$\begin{aligned} & \rho \left(\frac{\partial u_\varphi}{\partial t} + u_r \frac{\partial u_\varphi}{\partial r} + u_z \frac{\partial u_\varphi}{\partial z} + \frac{1}{r} \left[u_\varphi \frac{\partial u_\varphi}{\partial \varphi} + u_r u_\varphi \right] \right) \\ & = -\frac{1}{r} \frac{\partial p}{\partial \varphi} + \eta \left(\Delta u_\varphi - \frac{1}{r^2} \left[u_\varphi - 2 \frac{\partial u_r}{\partial \varphi} \right] \right) \end{aligned} \quad (\text{V.43})$$

$$\begin{aligned} & \rho \left(\frac{\partial u_z}{\partial t} + u_r \frac{\partial u_z}{\partial r} + u_z \frac{\partial u_z}{\partial z} + \frac{1}{r} u_\varphi \frac{\partial u_z}{\partial \varphi} \right) \\ & = -\frac{\partial p}{\partial z} + g_z + \eta \Delta u_z \end{aligned} \quad (\text{V.44})$$

V.5 Kugelkoordinaten**Umrechnung**

$$x = r \sin \vartheta \cos \varphi, \quad y = r \sin \vartheta \sin \varphi, \quad z = r \cos \vartheta \quad (\text{V.45})$$

$$r = \sqrt{x^2 + y^2 + z^2}, \quad \cos \vartheta = \frac{z}{\sqrt{x^2 + y^2 + z^2}}, \quad \tan \varphi = \frac{y}{x} \quad (\text{V.46})$$

$$\begin{aligned} \mathbf{e}_r &= \sin \vartheta \cos \varphi \mathbf{e}_x + \sin \vartheta \sin \varphi \mathbf{e}_y + \cos \vartheta \mathbf{e}_z \\ \mathbf{e}_\vartheta &= \cos \vartheta \cos \varphi \mathbf{e}_x + \cos \vartheta \sin \varphi \mathbf{e}_y - \sin \vartheta \mathbf{e}_z \\ \mathbf{e}_\varphi &= -\sin \varphi \mathbf{e}_x + \cos \varphi \mathbf{e}_y \end{aligned} \quad (\text{V.47})$$

$$\begin{aligned} \mathbf{e}_x &= \sin \vartheta \cos \varphi \mathbf{e}_r + \cos \vartheta \cos \varphi \mathbf{e}_\vartheta - \sin \varphi \mathbf{e}_\varphi \\ \mathbf{e}_y &= \sin \vartheta \sin \varphi \mathbf{e}_r + \cos \vartheta \sin \varphi \mathbf{e}_\vartheta + \cos \varphi \mathbf{e}_\varphi \\ \mathbf{e}_z &= \cos \vartheta \mathbf{e}_r - \sin \vartheta \mathbf{e}_\vartheta \end{aligned} \quad (\text{V.48})$$

Ableitung der Einheitsvektoren Die ersten Ableitungen der Einheitsvektoren nach r , ϑ und φ sind null bis auf

$$\frac{\partial \mathbf{e}_r}{\partial \vartheta} = \mathbf{e}_\vartheta, \quad \frac{\partial \mathbf{e}_\vartheta}{\partial \vartheta} = -\mathbf{e}_r, \quad \frac{\partial \mathbf{e}_r}{\partial \varphi} = \sin \vartheta \mathbf{e}_\varphi, \quad \frac{\partial \mathbf{e}_\vartheta}{\partial \varphi} = \cos \vartheta \mathbf{e}_\varphi, \quad \frac{\partial \mathbf{e}_\varphi}{\partial \varphi} = \mathbf{e}_z \wedge \mathbf{e}_\varphi \quad (\text{V.49})$$

Gradient

$$\nabla \Phi = \frac{\partial \Phi}{\partial r} \mathbf{e}_r + \frac{1}{r} \frac{\partial \Phi}{\partial \vartheta} \mathbf{e}_\vartheta + \frac{1}{r \sin \vartheta} \frac{\partial \Phi}{\partial \varphi} \mathbf{e}_\varphi \quad (\text{V.50})$$

Divergenz

$$\nabla \cdot \mathbf{f} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 f_r) + \frac{1}{r \sin \vartheta} \frac{\partial}{\partial \vartheta} (\sin \vartheta f_\vartheta) + \frac{1}{r \sin \vartheta} \frac{\partial f_\varphi}{\partial \varphi} \quad (\text{V.51})$$

Rotation

$$\begin{aligned} \nabla \wedge \mathbf{f} &= \frac{1}{r^2 \sin \vartheta} \begin{vmatrix} \mathbf{e}_r & r\mathbf{e}_\vartheta & r \sin \vartheta \mathbf{e}_\varphi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \vartheta} & \frac{\partial}{\partial \varphi} \\ f_r & r f_\vartheta & (r \sin \vartheta) f_\varphi \end{vmatrix} \\ &= \frac{1}{r \sin \vartheta} \left(\frac{\partial}{\partial \vartheta} (\sin \vartheta f_\varphi) - \frac{\partial f_\vartheta}{\partial \varphi} \right) \mathbf{e}_r + \frac{1}{r} \left(\frac{1}{\sin \vartheta} \frac{\partial f_r}{\partial \varphi} - \frac{\partial}{\partial r} (r f_\varphi) \right) \mathbf{e}_\vartheta \\ &\quad + \frac{1}{r} \left(\frac{\partial}{\partial r} (r f_\vartheta) - \frac{\partial f_r}{\partial \vartheta} \right) \mathbf{e}_\varphi \end{aligned} \quad (\text{V.52})$$

Laplace–Operator (skalar)

$$\Delta \Phi = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial \Phi}{\partial r} \right) + \frac{1}{r^2 \sin \vartheta} \frac{\partial}{\partial \vartheta} \left(\sin \vartheta \frac{\partial \Phi}{\partial \vartheta} \right) + \frac{1}{r^2 \sin^2 \vartheta} \frac{\partial^2 \Phi}{\partial \varphi^2} \quad (\text{V.53})$$

V.5.1 Wärmeleitungsgleichung**Wärmefluss**

$$\mathbf{q} = -k \nabla T = -k \left(\frac{\partial T}{\partial r} \mathbf{e}_r + \frac{1}{r} \frac{\partial T}{\partial \vartheta} \mathbf{e}_\vartheta + \frac{1}{r \sin \vartheta} \frac{\partial T}{\partial \varphi} \mathbf{e}_\varphi \right) \quad (\text{V.54})$$

Wärmeleitungsgleichung ($k = \text{const}$)

$$\rho C \frac{\partial T}{\partial t} - k \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial T}{\partial r} \right) + \frac{1}{r^2 \sin \vartheta} \frac{\partial}{\partial \vartheta} \left(\sin \vartheta \frac{\partial T}{\partial \vartheta} \right) + \frac{1}{r^2 \sin^2 \vartheta} \frac{\partial^2 T}{\partial \varphi^2} \right] = Q \quad (\text{V.55})$$